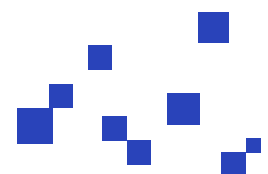
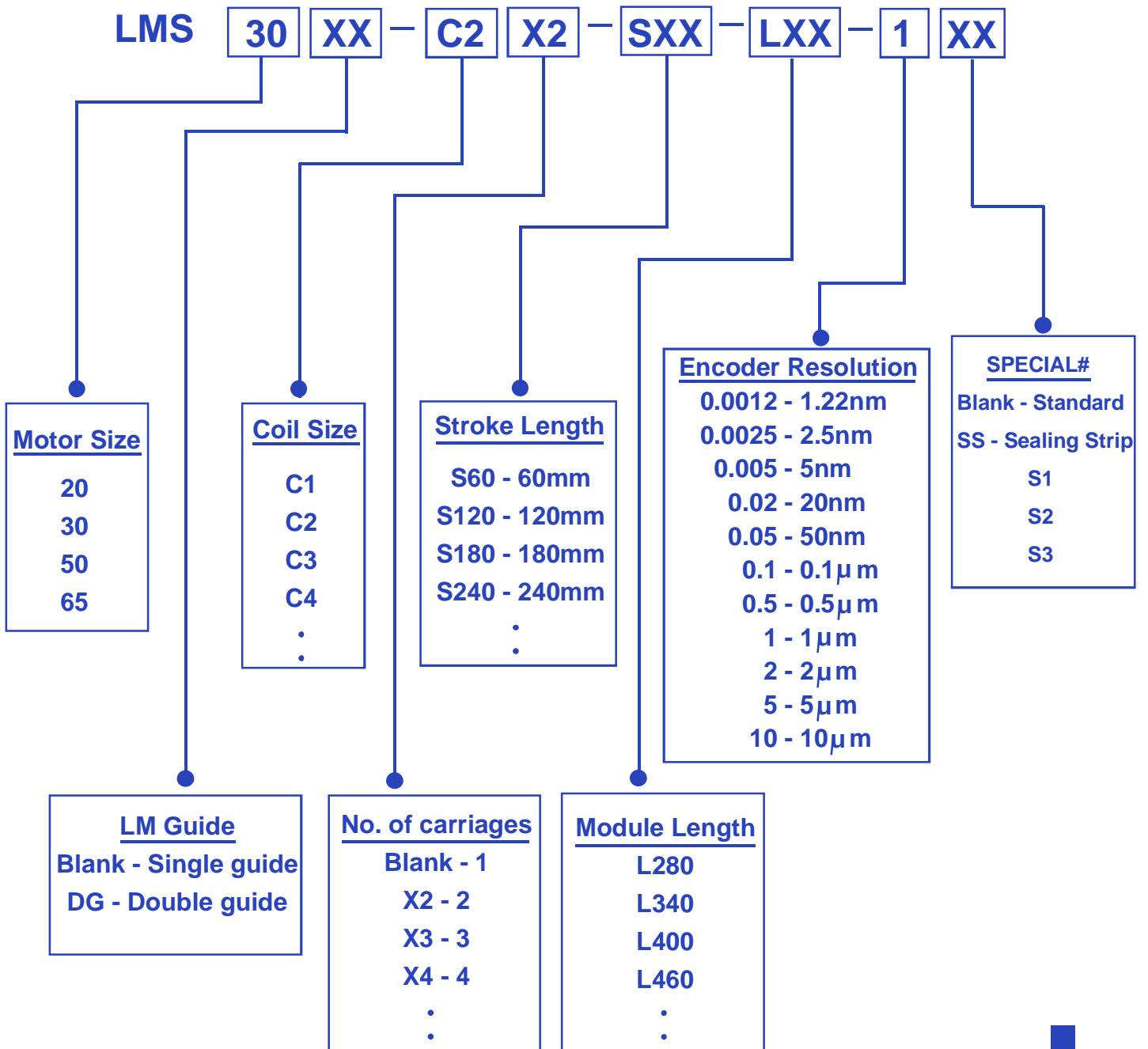


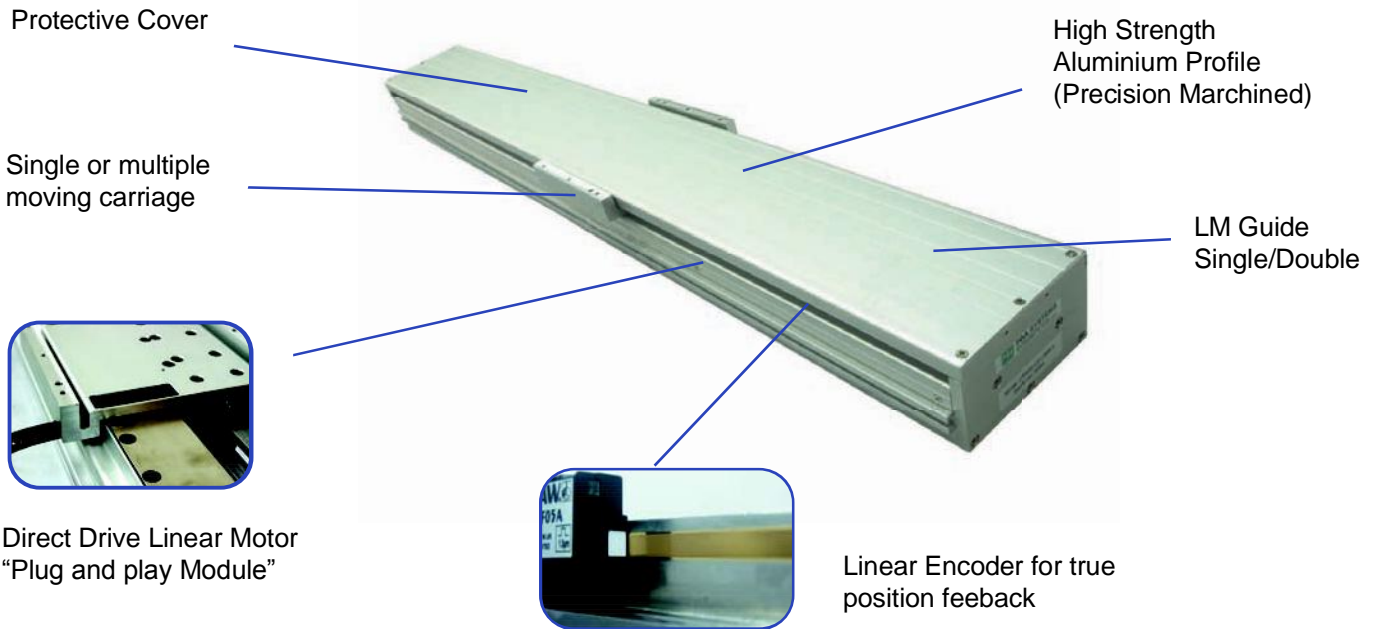
LMS SERIES



Part Numbering System

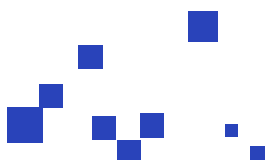


Features of LMS Series Linear Motor Actuators



Comparison With Traditional Actuators

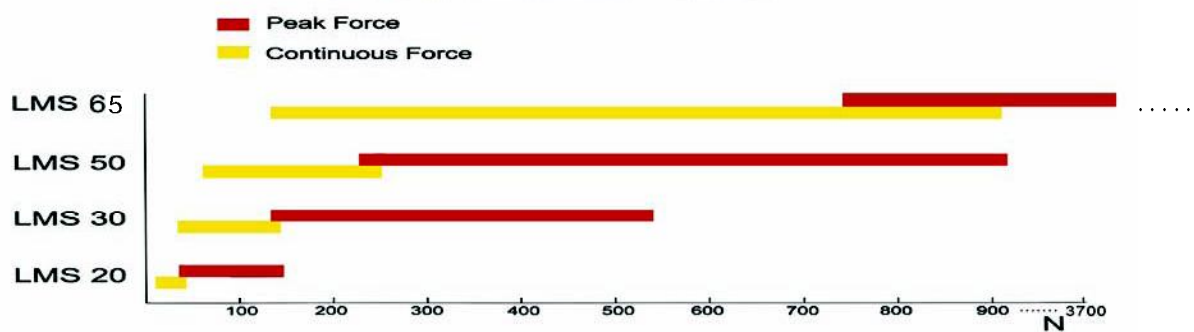
Features	Ball Screw Actuators	Timing Belt Actuators	LMS Series Linear Motor Actuators
Speed	Max 1.5 m/s	Max 3.5 m/s	Max 20 m/s
Motor	Rotary Servo Motor	Rotary Servo Motor	Linear Servo Motor
Backlash	3 μ m - 5 μ m	10 μ m - 100 μ m	Zero Backlash
Servo Feedback/Accuracy	Rotary Encoder	Rotary Encoder	Linear encoder (Measure actual linear position)
Dirve Design	Complicated (Many mechanical parts)	Complicated (Many mechanical parts)	Simple design (Direct drive)
Reliability	Wear and Tear (high maintenance)	Wear and Tear (high tensioning required periodically)	Least maintenance (no contact between coil & track)
Smoothness	Noisy when moving fast	Noisy	Smooth Motion



LMS Series Linear Motor Specifications

Model Number	Resolution (μm)	Max. Velocity (m/s)	Straightness (μm)
LMS20	0.05	1	20
LMS30	0.1	0.5	20
LMS50	0.5	1.5	20
LMS30DG	1.0	4.0	20
LMS50DG	5.0	5.0	20
LMS65DG	10	5.0	30

Force Selection Chart

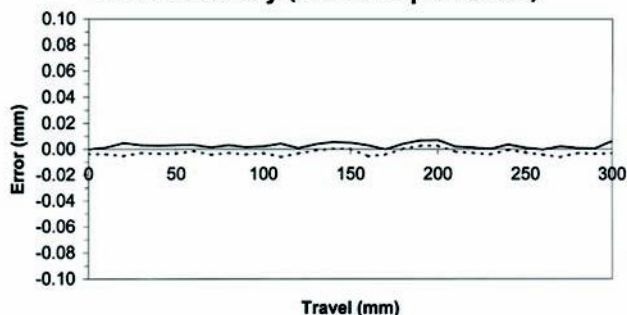


Accuracy Evaluation



State-of-the-art laser Calibration systems are utilized for verifying LM series linear motor actuators accuracy and performance specifications.

Linear Accuracy (with compensation)



Straightness

